First-order filters

The general form for the transfer function of a first order filter is:

$$T(s) = \frac{a_1 s + a_0}{b_1 s + b_o}$$

However, we will typically recast this into a standard form:

$$T(s) = G_o \cdot \frac{s + Z_o}{s + P_o}$$

There will always be a single pole at $s = -P_o$. The pole must be real (there is only one, so no complex conjugates are not possible) and it must be negative (for stability). There will always be a zero, which can be at s = 0, as $s \rightarrow \pm \infty$ (zero at infinity), or somewhere else, $s = -Z_o$. (Note the zero can have a positive value.) There may be a gain factor, G_o , which might be 1 or smaller (for a passive circuit with a voltage divider) or have a magnitude greater than 1 for an active circuit.

The two most important cases are the zero at infinity, which is a lowpass filter and the zero at zero, which is the high-pass filter.

Low-pass

In the case were $a_1 = 0$, we have a low-pass function. \int_{A}^{ω} s-plane

$$T(s) = \frac{a_o}{b_1 s + b_o}$$

In standard form, we write it as:

$$T(s) = G_o \cdot \frac{P_o}{s + P_o}$$

The reason for this form will become clear as we proceed. We will ignore the gain initially and focus on sinusoidal behavior by letting $s = j\omega$.

$$\frac{P_o}{s+P_o}\bigg|_{s=j\omega} = \frac{P_o}{P_o+j\omega}$$

Re-expressing the complex value in magnitude and phase form:

$$\frac{P_o}{P_o + j\omega} = \left[\frac{P_o}{\sqrt{P_o^2 + \omega^2}}\right] \exp\left(j\theta_{LP}\right) \qquad \theta_{LP} = -\arctan\left(\frac{\omega}{P_o}\right)$$

zero as s $\rightarrow \pm \infty$

pole at $-P_0$

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By looking at the magnitude expression, we can see the low-pass behavior.

For low frequencies ($\omega \ll P_o$): $\frac{P_o}{\sqrt{P_o^2 + \omega^2}} \approx \frac{P_o}{\sqrt{P_o^2}} = 1.$ At high frequencies ($\omega \gg P_o$): $\frac{P_o}{\sqrt{P_o^2 + \omega^2}} \approx \frac{P_o}{\sqrt{\omega^2}} = \frac{P_o}{\omega}.$

At low frequencies, the magnitude is 1 (the output is equal to the input) and at high frequencies, the magnitude goes down inversely with frequency, consistent with the notion of a low-pass response.

We can also examine the phase at the extremes.

For low frequencies (
$$\omega \approx 0$$
): $\theta_{LP} = -\arctan\left(\frac{\omega}{P_o}\right) \approx 0$.
At high frequencies ($\omega \rightarrow +\infty$): $\theta_{LP} = -\arctan\left(\frac{\omega}{P_o}\right) \approx -90^\circ$.

We can use the functions to make the magnitude $M = \frac{P_o}{\sqrt{P_o^2 + \omega^2}}$ and phase as frequency response plots.



Cut-off frequency

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Use the standard definition for cut-off frequency, which is the frequency at which the magnitude is down by $\sqrt{2}$ from the value in the pass-band. For our low-pass function, the pass band is at low frequencies, and the magnitude there is 1. (Again, we are "hiding" G_o by assuming that it is unity. If $G_o \neq 1$, then everything is scaled by G_o .)

$$M = \frac{1}{\sqrt{2}} = \frac{P_o}{\sqrt{P_o^2 + \omega_c^2}}$$

With a bit of algebra, we find that $\omega_c = P_o$. The cut-off frequency is defined by the pole. Tricky! Thus, in all of our equations, we could substitute ω_c for P_o .

We can also calculate the phase at the cut-off frequency.

$$\theta_{LP} = -\arctan\left(\frac{\omega_c}{P_o}\right) = -45^\circ$$

The cut-off frequency points are indicated in the plots on the previous slide.

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To emphasize the importance of the corner frequency in the low-pass function, we can express all the previous results using ω_c in place of P_o . On the left are the functions in "standard" form. On the right, the functions are expressed in a slightly different form that is sometimes easier to use.

$$T_{LP}(s) = G_o \cdot \frac{\omega_c}{s + \omega_c} \qquad T_{LP}(s) = \frac{G_o}{1 + \frac{s}{\omega_c}}$$
$$T_{LP}(j\omega) = G_o \cdot \frac{\omega_c}{j\omega + \omega_c} \qquad T_{LP}(j\omega) = \frac{G_o}{1 + j\left(\frac{\omega}{\omega_c}\right)}$$
$$|T_{LP}(j\omega)| = |G_o|\frac{\omega_c}{\sqrt{\omega^2 + \omega_c^2}} \qquad |T_{LP}(j\omega)| = \frac{|G_o|}{\sqrt{1 + \left(\frac{\omega}{\omega_c}\right)^2}}$$
$$\theta_{LP} = -\arctan\left(\frac{\omega}{\omega_c}\right) \qquad \theta_{LP} = -\arctan\left(\frac{\omega}{\omega_c}\right)$$

Again, we could just as easily use real frequency rather than angular frequency. As an exercise: re-express all of the above formulas using f instead of ω .

Low-pass filter circuits: simple RC

Resistor and capacitor in series — output taken across the capacitor.

Use a voltage divider to find the transfer function.

 $V_{o}\left(s\right) = \frac{Z_{C}}{Z_{C} + Z_{R}} V_{i}\left(s\right)$

$$T(s) = \frac{V_o(s)}{V_i(s)} = \frac{Z_C}{Z_C + Z_R} = \frac{\frac{1}{sC}}{\frac{1}{sC} + R} = \frac{\frac{1}{RC}}{s + \frac{1}{RC}} = \frac{\omega_c}{s + \omega_c}$$

Clearly, this is low-pass with $G_o = 1$ and $\omega_c = \frac{1}{RC}$

The only real design consideration is choosing the *RC* product, which then sets the corner frequency.

+

 $V_o(s)$

 $Z_R = R$

 $V_i(s)$

 $Z_{C} = 1$

Low-pass filter circuits: simple RL

Inductor and resistor in series — output taken across the resistor.

 $Z_{L} = sL$ $V_{i}(s) + Z_{R} \stackrel{}{\stackrel{}{\underset{\scriptstyle \leftarrow}{\scriptstyle \leftarrow}}} V_{o}(s)$ = R -

Use a voltage divider to find the transfer function.

 $V_{o}\left(s\right) = \frac{Z_{R}}{Z_{R} + Z_{I}} V_{i}\left(s\right)$

$$T(s) = \frac{V_o(s)}{V_i(s)} = \frac{Z_R}{Z_R + Z_L} = \frac{R}{R + sL} = \frac{\frac{R}{L}}{s + \frac{R}{L}} = \frac{\omega_c}{s + \omega_c}$$

Again, low-pass behavior with $G_o = 1$, but now with $\omega_c = \frac{R}{T}$

As with the previous example choosing the "RL time constant", we can define the pass-band of this low-pass filter.

Low-pass filter circuits: inverting op amp



$$T(s) = \frac{V_o(s)}{V_i(s)} = -\frac{Z_2}{Z_1} = -\frac{\frac{R_2}{1+sR_2C}}{R_1} = \frac{-\frac{R_2}{R_1}}{1+sR_2C} = \left(-\frac{R_2}{R_1}\right)\frac{\frac{1}{R_2C}}{s+\frac{1}{R_2C}}$$

Clearly, this is also low-pass with $G_o = -\frac{R_2}{R_1}$ and $\omega_c = \frac{1}{R_2C}$

Be careful with the extra negative sign in the gain: $-1 = \exp(j180^\circ)$ At low frequencies: $|T| \rightarrow R_2/R_1$, and $\theta_T \rightarrow 180^\circ (= -180^\circ)$ At high frequencies: $|T| \rightarrow (\omega R_1 C)^{-1}$, and $\theta_T \rightarrow +90^\circ (= -270^\circ)$ Magnitude and phase plots for an active low-pass filter with $R_1 = 1 \text{ k}\Omega$, $R_2 = 25 \text{ k}\Omega$, and C = 6.4 nF, giving $f_0 = 1000 \text{ Hz}$ and $G_0 = -25 (|G_0| = 28 \text{ dB})$.



Low-pass filter circuits: non-inverting op amp



Low-pass with $G_o = \left(1 + \frac{R_2}{R_1}\right)$ and $\omega_c = \frac{1}{RC}$

Note: It might slightly disingenuous to treat this as if it were some new type of filter — we can readily see that it is a simple RC filter cascaded with a simple noninverting amp. However, it is still a useful circuit.

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High-pass

In the case were $a_0 = 0$, we have a high-pass function.

$$\overset{\omega}{\bullet}$$
 s-plane

zero at 0

pole at $-P_0$

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$$T(s) = \frac{a_1 s}{b_1 s + b_0}$$

In standard form, we write it as:

$$T(s) = G_o \cdot \frac{s}{s + P_o}$$

We will ignore the gain initially (set $G_o = 1$) and focus on sinusoidal behavior by letting $s = j\omega$.

$$\frac{s}{s+P_o}\bigg|_{s=j\omega} = \frac{j\omega}{P_o+j\omega}$$

Re-expressing the complex value in magnitude and phase form:

$$\frac{j\omega}{P_o + j\omega} = \left[\frac{\omega}{\sqrt{P_o^2 + \omega^2}}\right] \exp\left(j\theta_{HP}\right) \qquad \theta_{HP} = 90^\circ - \arctan\left(\frac{\omega}{P_o}\right)$$

By looking at the magnitude expression, we can see the high-pass behavior.

For low frequencies ($\omega \ll P_o$): $\frac{\omega}{\sqrt{P_o^2 + \omega^2}} \approx \frac{\omega}{\sqrt{P_o^2}} = \frac{\omega}{P_o}$.

At high frequencies ($\omega >> P_o$): $\frac{\omega}{\sqrt{P_o^2 + \omega^2}} \approx \frac{\omega}{\sqrt{\omega^2}} = 1.$

At low frequencies, the magnitude is increasing with frequency, and at high frequencies, the magnitude is 1 (the output is equal to the input). This behavior is consistent with a high-pass response.

We can also examine the phase at the extremes.

For low frequencies ($\omega \ll P_o$): $\theta_{HP} = 90^\circ - \arctan\left(\frac{\omega}{P_o}\right) \approx 90^\circ$. At high frequencies ($\omega \gg P_o$): $\theta_{HP} = 90^\circ - \arctan\left(\frac{\omega}{P_o}\right) \approx 0^\circ$.

ω We can use the functions to make the magnitude M = - $P_o^2 + \omega^2$ and phase as frequency response plots. magnitude - linear scale magnitude - Bode plot 1.2 10 1.0 0 magnitude (dB) 0.8 -10 magnitude -20 0.6 -30 0.4 0.2 -40 0.0 -50 100 1000 10 10000 100000 100 1000 10000 100000 10 angular frequency (rad/s) angular frequency (rad/s) phase 90 75 $\theta_{HP} = 90^{\circ} - \arctan\left(\frac{\omega}{P_o}\right)$ 60 phase (°) 45 30 15 0 10 100 1000 10000 100000 angular frequency (rad/s)

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Cut-off frequency

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Use the standard definition for cut-off frequency, which is the frequency at which the magnitude is down by $\sqrt{2}$ from the value in the pass-band. For our high-pass function, the pass band is at high frequencies, and the magnitude there is 1. (Again, we are "hiding" G_o by assuming that it is unity. If $G_o \neq 1$, then everything is scaled by G_o .)

$$M = \frac{1}{\sqrt{2}} = \frac{\omega}{\sqrt{P_o^2 + \omega_c^2}}$$

With a bit of algebra, we find that $\omega_c = P_o$. The same result as for lowpass response, except that pass-band is above the cut-off frequency in this case. Once again, we see the importance of the poles in determining the behavior of the transfer functions.

We can calculate the phase at the cut-off frequency.

$$\theta_{HP} = 90^\circ - \arctan\left(\frac{\omega_c}{P_o}\right) = 45^\circ$$

The cut-off frequency points are indicated in the plots on the previous slide.

To emphasize the importance of the corner frequency in the high-pass function, we can express all the previous results using ω_c in place of P_o .

$$\frac{G_o}{\sqrt{2}} = \frac{G_o \cdot P_0}{\sqrt{\omega_c^2 + P_0^2}} \rightarrow P_0 = \omega_c \qquad \text{The corner frequency is the value of the pole.} \\ T_{HP}(s) = G_o \cdot \frac{s}{s + \omega_c} \qquad T_{HP}(s) = \frac{G_o}{1 + \frac{\omega_c}{s}} \\ T_{HP}(j\omega) = G_o \cdot \frac{j\omega}{j\omega + \omega_c} \qquad T_{HP}(j\omega) = \frac{G_o}{1 + \left(\frac{\omega_c}{j\omega}\right)} \\ |T_{LP}(j\omega)| = G_o \cdot \frac{\omega}{\sqrt{\omega^2 + \omega_c^2}} \qquad = \frac{G_o}{1 - j\left(\frac{\omega_c}{\omega}\right)} \\ \theta_{HP} = \arctan\left(\frac{\omega}{0}\right) - \arctan\left(\frac{\omega}{\omega_c}\right) \qquad |T_{HP}(j\omega)| = \frac{G_o}{\sqrt{1 + \left(\frac{\omega_c}{\omega}\right)^2}} \\ = 90^\circ - \arctan\left(\frac{\omega}{\omega_c}\right) \qquad \theta_{HP} = + \arctan\left(\frac{\omega_c}{\omega}\right) \\ ercise: \text{ Re-express all of the above formulas using f instead of } \omega. \end{cases}$$

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High-pass filter circuits: simple RC

Capacitor and resistor in series — output taken across the resistor.

Use a voltage divider to find the transfer function.

$$V_{o}\left(s\right) = \frac{Z_{R}}{Z_{C} + Z_{R}} V_{i}\left(s\right)$$

$$T(s) = \frac{V_o(s)}{V_i(s)} = \frac{Z_R}{Z_R + Z_C} = \frac{R}{R + \frac{1}{sC}} = \frac{s}{s + \frac{1}{RC}} = \frac{s}{s + \omega_c}$$

 $V_i(s)$

Clearly, this is high-pass with $G_o = 1$ and $\omega_c = \frac{1}{RC}$

 $\frac{Z_C}{||} = \frac{1}{sC}$

 $V_o(s)$

High-pass filter circuits: simple RL



 $V_{o}\left(s\right) = \frac{Z_{L}}{Z_{L} + Z_{R}} V_{i}\left(s\right)$

$$T(s) = \frac{V_o(s)}{V_i(s)} = \frac{Z_L}{Z_L + Z_R} = \frac{sL}{sL + R} = \frac{s}{s + \frac{R}{L}} = \frac{s}{s + \omega_c}$$

Again, high-pass with $G_o = 1$ but with $\omega_c = \frac{R}{T}$

High-pass filter circuits: inverting op amp





$$T(s) = \frac{V_o(s)}{V_i(s)} = -\frac{Z_2}{Z_1} = -\frac{R_2}{R_1 + \frac{1}{sC}} = \left(-\frac{R_2}{R_1}\right)\frac{s}{s + \frac{1}{R_1C}}$$

We see that this is also high-pass with $G_o = -\frac{R_2}{R_1}$ and $\omega_c = \frac{1}{R_1C}$

The same comments about the phase apply here: the -1 in the gain factor introduces an extra 180° (or -180°) of phase.

High-pass filter circuits: non-inverting op amp



Again, this is simple RC highpass cascaded with a noninverting amp.

non-inverting amp

High-pass filter circuits: another RC

$$T(s) = \frac{V_{o}(s)}{V_{i}(s)} = \frac{Z_{R2}}{Z_{R2} + Z_{R1} + Z_{C}}$$

$$= \frac{R_{2}}{R_{2} + R_{1} + \frac{1}{sC}}$$

$$V_{i}(s) + V_{i}(s) + V_{i}(s) + V_{i}(s)$$

$$= R_{2} + V_{o}(s)$$

$$= \left(\frac{R_{2}}{R_{1} + R_{2}}\right) \frac{s}{s + \frac{1}{(R_{1} + R_{2})C}}$$

$$= G_{o} \cdot \frac{s}{s + \omega_{c}}$$
High-pass.

$$G_{o} = \frac{R_{2}}{R_{1} + R_{2}}$$
Note the voltage divider. "Gain" < 1.

$$\omega_{c} = \frac{1}{(R_{1} + R_{2})C}$$
The corner depends on the series combination.

Case study: inductors can be trouble

Cheap inductors can have a relatively large series resistance. This *parasitic* resistance can cause trouble in certain circumstances.





Effect of inductor parasitic resistance on high-pass filter: L = 0.027 H, $R_1 = 1$ k Ω , and $R_s = 60$ Ω .

The frequency responses for both magnitude and phase are quite different.

